

## Proportional directional valves with linear motor

# PRL1

Size 06 (D03) • Q<sub>max</sub> 63 l/min (17 GPM) • p<sub>max</sub> 350 bar (5100 PSI)

### **Technical Features**

- > Proportional directional control valve with high response speed to a change of command signal
- > Connecting diagram size 06 according to standards ISO 4401 and DIN 24340 (CETOP 03)
- The valve is suitable for continuous control of flow rate or pressure (as a pilot valve)
  - proportionally to the input command signal
- It is designed for control of hydraulic cylinders and rotational hydraulic motors
- High reliability of design solution
- > It is required the same cleanliness degree of the working fluid as at standard valves
- The direct spool control improves the dynamic of valve and reduces dependence on operating pressure
- Valve control with external or integrated electronic control unit in the form of connector plug (ECU)
- Additionally, the valve can be equipped with a manual override of valve spool >
- and as preparation for painting. Steel parts are zinc-coated for 240 h salt spray protection acc. to ISO 9227 In the standard version, the valve housing is phosphated for basic surface corrosion protection

Technical Data											
			06 (D02)								
Max operating prossure											
Pated flow Ap 70 bar			16 (4 22)	22 (0 4E)	130(2180)						
Rated flow $\Delta p = 70$ bar	I/min (GPIVI)	5.2 (0.65)	10(4.23)	32 (0.45)	25 (10.0)						
Nated 1000 $\Delta p = 10$ bal		1.1 (0.29)	1.1 (0.29) 0.3 (1.00) 12.5 (3.3)								
Max current coil for 24 V	A	2 5									
Hystorosis	Max. current coll for 24 V A				2.5						
Threshold	Hysteresis %				< /						
Fluid temperature range	Infeshold %										
Ambient temperature max	Indicite C (°F)   Import tomporature max °C (°F)				-30 +80 (-22 +170)						
Weight	.mplent temperature, max. C (*F)										
vveignt Kg (ibs) 1.8 (3.97)											
Flow losses in l/min		Spool lap									
(at input pressure 100 bar, viscosity	y 32 mm²/s an	d middle positi	on of spool)								
		0	1	2	3						
PRL1-06-0324 (12)		< 0.8	< 0.2	< 0.2	< 2.0						
PRL1-06-1624 (12)	l/min	< 1.5	< 0.2	< 0.2	-						
PRL1-06-3224 (12)	VIIIII	< 1.5	< 0.2	< 0.2	-						
PRL1-06-6324 (12)		< 1.5	< 0.2	< 0.2	-						
Technical data of electronic contro	l unit FL7										
Operating supply voltage Licc		9 32									
Reference voltage Uref	Reference voltage Liref				5						
Max current at Uref	20										
Types of input command signal w	d	see datasheet EL7*									
Max. output current / 1 coil	A	-	3								
PWM frequency	Hz		80 1000								
Resolution of A/D converters	bit		12								
Ramp function	S		0 45								
Dither – amplitude*	% from Ima	x	0 30 % from Imax								
Dither – frequency*	Hz		60 300								
* When the dither is activated, the PWM frequency is automatically set to 15 kHz											
	Datasheet		lype								
General information	GI_0060		Products and operating conditions								
Mounting interface	SM1_0019	2)	Size 06								
Subplates	DP-04 (06, 1	0)		Size 06							
Spare parts											

## **Spool Symbols**

ISO 4401-03-02-0-05

31,75 (1.25)

В

25,9 (1.16) 31 (1.22)

Ports P, A, B, T - max Ø7,5 mm (0.29 in)

0,75 (0.03)

ŝ 5 (1.

0 0 30,2 5

5,1 (0.20) 15,5 (0.61)

,5 (0.85)

4xM5-6Hx13

12,7 (0.50)

Тур	PRL1-06	PRL1-06N
Z11		
Y11		
H11		



## **Functional Description**

The PRL1 proportional directional control valve is designed for continuous remote control of rotational hydromotors and hydraulic cylinders in mobile and stationary applications. Direct spool operation by linear motor and robust design increase valve function reliability and reduce the required cleanliness of the working fluid. The hydraulic part consists of a cast-iron body with a fitted spool. The control part consists of a linear motor. The armature of the linear motor is centred by springs and the working gaps are premagnetized in opposite directions by permanent rare earth magnets. When the coil is energized, the armature with spool moves from the middle position. Spool position and volumetric flow are proportional to the control current. The moving direction of the spool and flow direction depend on current flow direction. In the event of supply voltage disconnection or cable failure the motor armature with the spool moves back to the basic middle position. The manual override allows smooth adjustment of the spool by screwing the hexagonal socket screw 4 in the flange.

The valve can be controlled by an external electronic control unit (EL7-E) or integrated electronic control unit (EL7-I) in the form of connector plug. Although the PRL1 proportional directional control valve is primarily designed for control of both flow direction and volume (size), it can be used for pressure control as a pilot valve for proportional directional control valves of larger sizes. Due to their dynamic properties the PRL1 proportional directional directional control systems.

### Electronic control unit EL7

The ECU EL7 allows direct independent control of the valve with an analogue input command signal or connection of the valve to the CANBus control system of a machine.

Valve with a bipolar linear motor controlled by external electronic control unit EL7-E

The valve can be controlled by external ECU EL7-E designed for connection to a DIN rail. The user electrically connects the ECU to the valve with a cable.

Selection and setting of ECU parameters is described in datasheet HA 9152.

#### Valve with a bipolar linear motor controlled by integrated electronic control unit EL7-I

The ECU in the form of connector plug is simply mounted on the socket of connector EN 175301-803-A of solenoid coil and fastened with a fixing screw.

Selection and setting of ECU parameters is described in datasheet HA 9151.

## Ordering Code

oracini	geoue												
Propor	tional dire	ectional	valves	PRI	.1-06-	-	-						
with lin	near moto	r											Model
									No designation	n			basic
Nomina	al size								N		manual	override o	on the valve
ISO 440	1-03-02-0	-05,											
DIN 243	840 (CETO	P 03), siz	e 06							Inte	grated ele	ectronic co	ontrol unit
Nomin	al flow in	l/min at	t tha n	essure differen	<b>CO</b>				lesignation	ropic EL 7	Wi A Divite	thout integ	grated ECU
at the v	al now in alve	i/iiiii a	t the pi	essure unreren	ce			EL/-	C Electronic	- FI 7-IC-3	for conne	ection to th	nput signal
	(4045)		(4 4 5)						e Electronic				
Δp 70	(1015)	∆p 10	(145)	[bar (PSI)]							Spoo	ol lap	
3.2	(0.8)	1.1	(0.29)	[I/min (GPM)]	03					0	1	2	3
16	(4.2)	6.3	(1.7)	[I/min (GPM)]	16			PRI 1-	06-0324 (12)	•	•	•	•
32	(8.5)	12.5	(3.3)	[l/min (GPM)]	32			PRI 1-06-1624 (12)		•	•	•	
63	(16.6)	25.0	(6.6)	[l/min (GPM)]	63			PRI 1-	06-3224 (12)	0	0	0	
								DRI 1	06-6324 (12)	0	0	0	
Spool I	ар							FILLI-	00-0324 (12)	9	9	0	
"Z" zero			0	• common types									
$_{\mu}Z^{\mu}Z^{5}$ % overlap			1	• restricted max. parameters.									
" I 20 % Overlap H" pressure valve			2	Additional flow rates delivered by request									
"ii pie	sourd valve					5		Au		uenverec	i by reques	i.	

### **Frequency Response**

**PRL1-06-16-0-24** p<sub>o</sub> = 100 bar x = 25 %







3

4

5

 $p_0 = 100 \text{ bar} (1450 \text{ PSI})$ 

 $p_0 = 200 \text{ bar} (2900 \text{ PSI})$ 

 $p_0 = 350 \text{ bar} (5076 \text{ PSI})$ 

3

4

PRL1-06-32-.-24 (12)

PRL1-06-63-.-24 (12)

max. 150 bar (2180 PSI)





#### **Dimensions** in millimeters (in)

## PRL1-06-..-..



## PRL1-06-..-.N



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